

# **X-Band Radar: More Than a Source for Airborne Weather**

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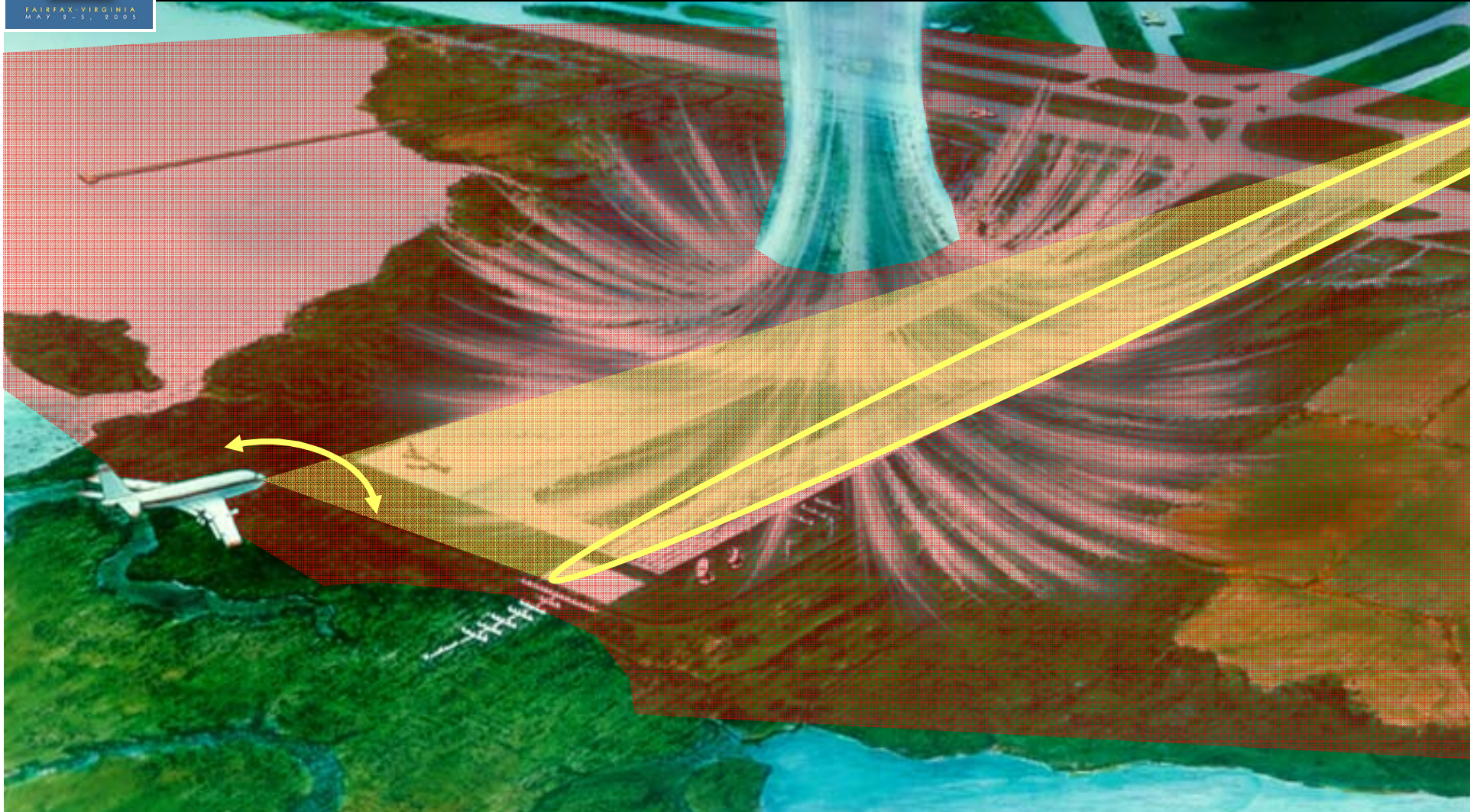
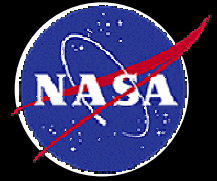
**Thursday 05 May 2005**





## Wind Shear Detection

Radar must look down onto the ground, spatially and temporally resolve wind field, separating weather signatures from ground clutter/signatures



*Now installed on all large commercial (most military) transport aircraft,  
more than 8000 installations resulting in over \$1B in revenues*



## Non-Cooperative Aircraft Tracking

**TFE:** Terrain Feature Extraction

Variety of implementations/displays, for SVS  
uses GPS Position and DTED to Confirm/Correct  
Database Registration (ie, one form of DIME) &  
Database Augmentation

## Runway Confirmation & Runway Incursion Detection

**All-WX Taxi:** Similar to RID but using taxiway  
templates and an ultra-short range radar mode  
Allows A/C to taxi to gate w/o GSR assistance

**NCAT:** Non-Cooperative Aircraft Tracking

Developed under NASA HSR Program

Demonstrated Real-Time NCAT (1997/TIFST)

**R/W!:** Runway Confirmation

Uses Airport Characteristics (Approach Lights  
Terminal Location, Runway Edges, etc) to  
Confirm/Correct Registration

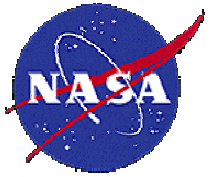
**RID:** Runway Incursion Detection

Using the known/measured runway location  
as a template we look for localized areas of  
significant NRCS contrast but alert ONLY on  
objects within the Runway template





## **HSR – XVS – RF Sensor Technologies**



***Develop/Integrate/Demonstrate RF Technologies which Enable the Development of A Commercially Viable Aircraft, Capable of Carrying 300 Passengers at Mach 2.5 over Trans-Pacific Routes, and at Operational Costs Comparable with Subsonic***

Traffic Surveillance for a “No Forward Window Cockpit”  
Maintain or Enhance Traffic/Terrain Awareness  
*(including non-cooperative traffic)*



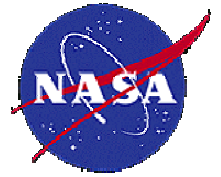
NCAT Video NASA Be-200







## Non-Cooperative Aircraft Tracking Requirements



**Range:** ~4Nm (500kts & 30s)

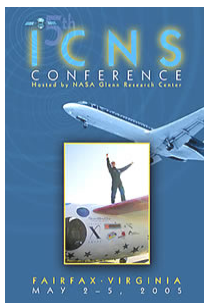
**$P_D$ :** 90%

**FoR:** 40°x50° (AxE)

**Update:** 8s (AAMT Augment: 10Hz)

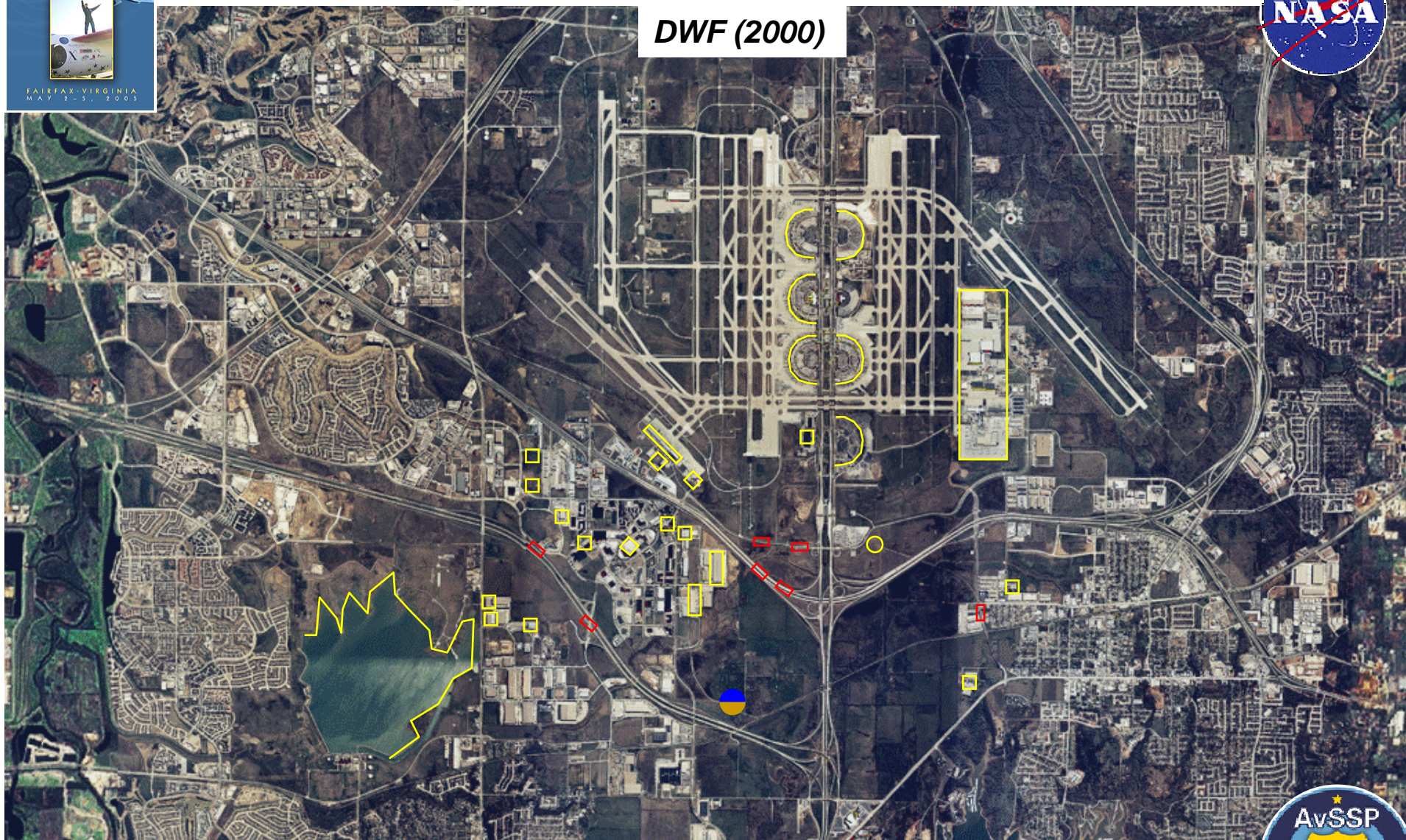
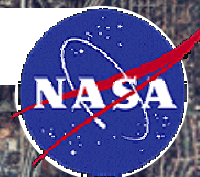






## High-Resolution Radar Ground Map

DWF (2000)



Expected Features

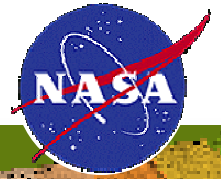
Moving Traffic

Confirm Location of Airport Features  
Urban / Man-Made Environment

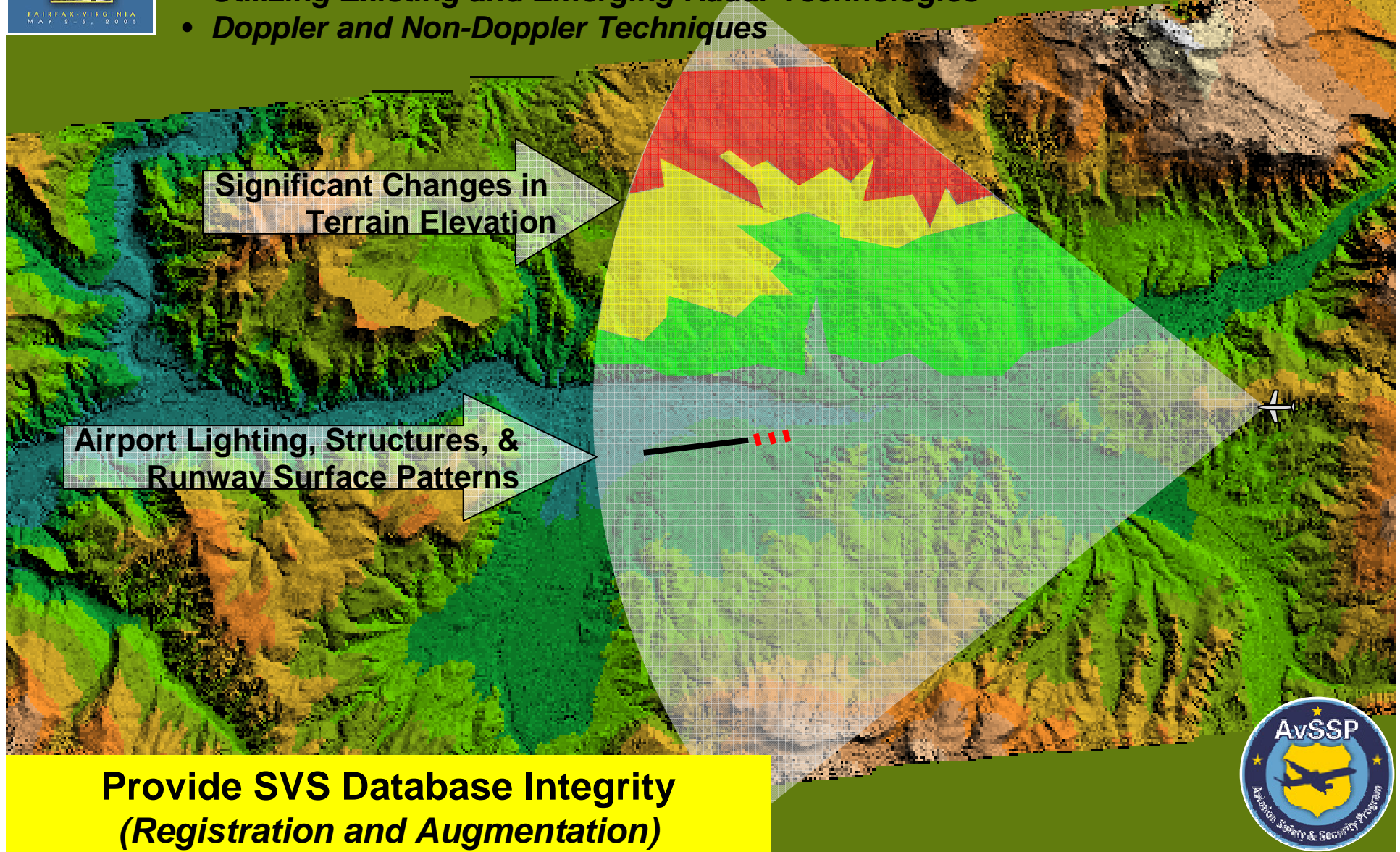




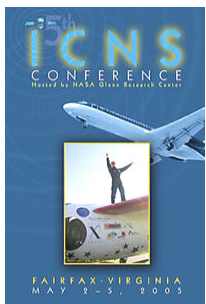
## Terrain Feature Extraction



- *Utilizing Existing and Emerging Radar Technologies*
- *Doppler and Non-Doppler Techniques*







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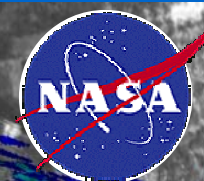
**Conventional WXR  
150 m x  $+3^\circ$  bins**

**Enhanced Vision Radar  
3 m x  $1/3^\circ$  bins**

**LFI  
NRCS**

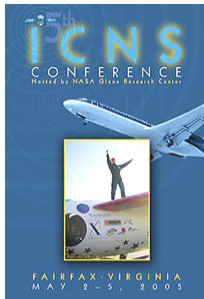
**Course  
bins**

**Fine  
bins**

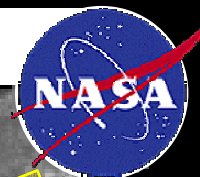


**Additional Resolution Allows for more Accurate Beam Fill & Therefore More Accurate Measurements**

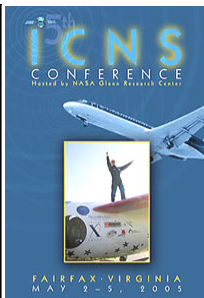




## ICF Test Set-up – LFI (RW! & RID)





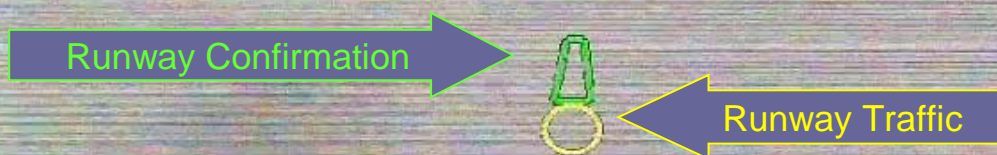


*AvSSP-Synthetic Vision Project  
Synthetic Vision Sensors Element*



**Runway Confirmation & Incursion Detection**

- May 2003 SVS ICF – NASA B757
- Near Instrument Meteorological Conditions
- Ceiling as Low as 200'
- Visibility < 1NM
- 20+ dBZ Rain (disables W-Band Radars)
- Video Start ~1.5NM or 35s from Runway Threshold (LFI)



T-30s < Advisory Warning < T-60s  
T-30s < Traffic Alert



# AvSSP – Synthetic Vision Systems Project

## Synthetic Vision Sensors Element



**Verifies and Supplements SVS Concept Utilizing Existing EVS Technologies** (Airborne Doppler Radar & FLIRs)

**Provides Incremental Technology Step Critical to SVS Deployment**



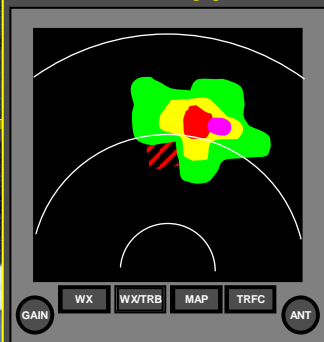
## Non-Cooperative Aircraft Tracking

DONE (HSR)  
KC-135 (\$400M+)  
Pacer CRAG

## Runway Confirmation & Runway Incursion Detection

DONE (SVS)  
RC & DoD

## Synthetic Vision Sensor Technologies Integrating & Building Upon Existing Airborne Doppler Radar & FLIR Technologies



Ongoing  
MaxViz &  
NASA

## Terrain Awareness

50% (SVS)  
AvSSP  $\phi 2$

## All-Weather Ground Operations

AvSSP  $\phi 2$